

# X7+ Pro Controller

## Product manual

2023-1-10



CUAV Tech Inc.,Ltd

## Disclaimer

Please read the manual carefully before using it to make sure that you can use it correctly and safely. You need to install and use this product in strict accordance with the instructions. CUAV is not liable for any loss due to improper use. This manual is only used as a user guide. The company reserves the right to modify and improve the product details and instructions. The relevant data shall be subject to the data provided by our staff. CUAV does not guarantee the accuracy and reliability of the contents of the document.

This product is only a pure hardware component of an experimental unmanned system, and the firmware and software are provided by a third party. X7+ Pro is only one of the components of unmanned system, and it has high requirements for use mode and compatibility of various components of unmanned system; CUAV only has the obligation to provide after-sales service within the product warranty period, and the company does not guarantee the reliability for any purpose; The company shall not be responsible for the direct, indirect, derivative, accidental injury and other losses or punishment caused by any reason or under any circumstances.

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## Product version history

This product is a continuation version of CUAV X7 Pro controller, compatible with all the expansion hardware of the above products; except for the different compatible firmware, users can seamlessly replace it.

## Online documentation

Please visit the CUAV docs for detailed tutorials and firmware downloads of this product:

<http://doc.cuav.net>

## Download ground control station











[QGroundControl:](#)

[https://docs.qgroundcontrol.com/en/getting\\_started/download\\_and\\_install.html](https://docs.qgroundcontrol.com/en/getting_started/download_and_install.html)

[Mission Planner:](#)

<https://firmware.ardupilot.org/Tools/MissionPlanner/MissionPlanner-stable.msi>

## Parts List

<h1>X7+ Pro Packing List</h1>		
X7+ Pro	X1	
I2C / CAN cable	X2	
ADC3.3 cable	X1	
RSSI cable(X7 series)	X1	
CAN PMU Lite Power Module	X1	
Dupont cable	X1	
CAN extension board	X1	
Pw-Link module	X1	
USB-TypeC cable	X1	
32G Memory card	X1	

## Hardware specifications

Item	Parameter
MCU	STM32H743
Accelerometer	ADIS16470/ICM-42688-P/ICM-20689/ICM-20689
Gyroscope	ADIS16470/ICM-42688-P/ICM-20689/ICM-20689
Barometer	MS5611*2

Interfaces	
UART	5
I2C	6(2 interfaces are integrated in GPS&SAFETY&UART4)
PWM output	14 (M1~M12 support dshot protocol)
RC in	1 ( Support PPM/SBUS/DSM)
RSSI input	PWM or 3.3 analog voltage
CAN bus	2
Power input	2 (Power A for ADC protocol; Power C for CAN protocol)
Safety switch	Integrated into GPS&SAFETY port
GPS interface	2
ADC	1
Debug	1
JATG	1
USB interface	1
Controller Working environment and physical Spec	
PM operating voltage	4.5 ~ 5.5 V
USB input voltage	4.75 ~ 5.25 V
Servo input	0 ~ 10v
Operating temp	-20 ~ 85°c
Humidity	5% ~ 95% (Does not condense)
Size	77.0 × 45.5 × 39.0 mm
Weight	103g

## Support firmware

X7+ Pro controller runs perfectly with ArduPilot 4.10/PX4 V1.12.3 and above firmware.

## Firmware and source code

**X7+ Pro supports PX4 and ArduPilot firmware, the compiled firmware**

**Download and write firmware tutorial:**

<https://doc.cuav.net/controller/x7/en/ardupilot-users-manual.html#ardupilot-firmware>

**If you want to modify the code; you can download the source code through the link below**

ArduPilot Github :

<https://github.com/ArduPilot/ardupilot>

PX4 Github :

<https://github.com/PX4/PX4-Autopilot>

**Compile firmware command(ArduPilot):**

```
./waf configure --board CUAV-x7 //Compile CUAV X7 branch firmware
./waf copter --upload //Write the firmware to the controller
```

**Compile firmware command(PX4):**

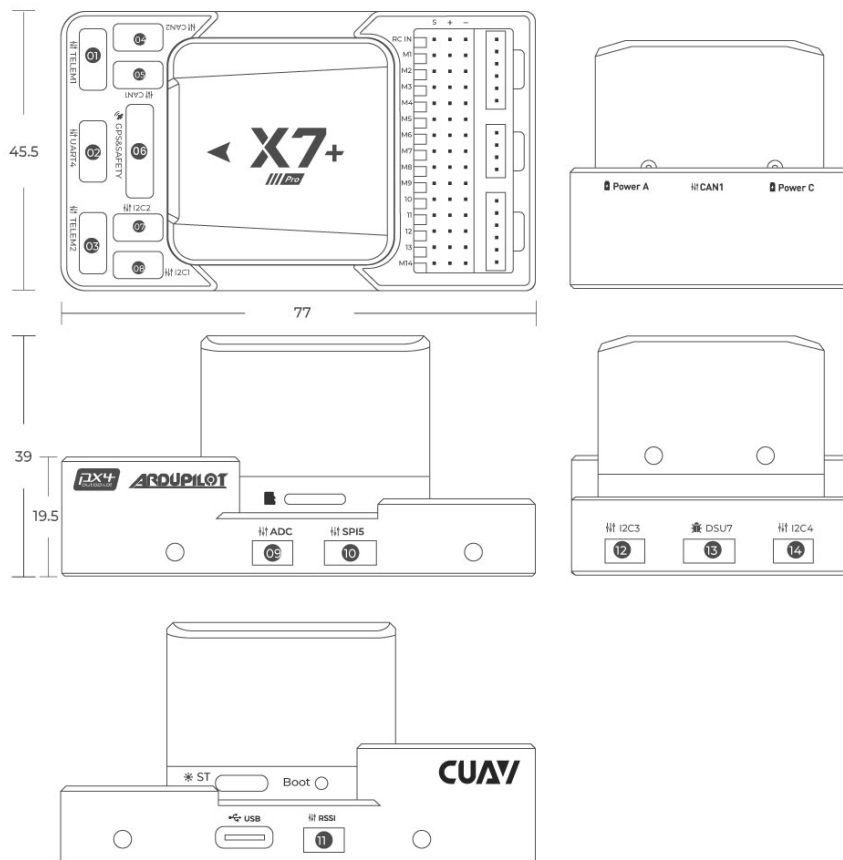
```
make cuav_x7pro_default //Compile CUAV X7 Pro branch firmware
```

**Note:**

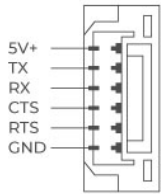
X7+ Pro supports (ArduPilot) CUAV X7 branch firmware and (PX4) CUAV X7 pro branch firmware.

**Pinouts**

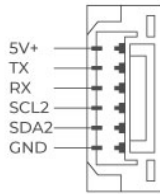
The design of the X7+ Pro interface uses Pixhawk standard pinouts. Please read the description of the interface definition carefully and use the original wiring of the product. If the wiring is not used according to the standard defined by the interface, the company will not compensate for the damage to the equipment.



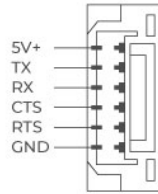
01 TELEM 1



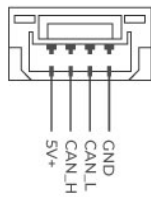
02 UART4



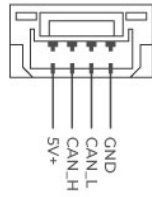
03 TELEM 2



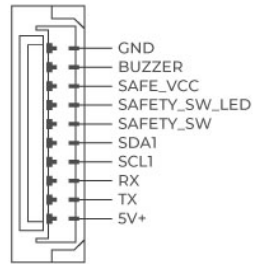
04 CAN 2



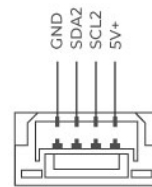
05 CAN 1



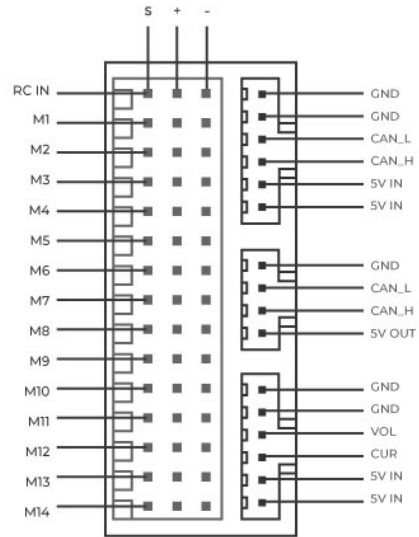
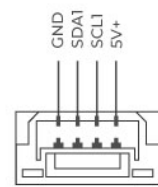
06 GPS&SAFETY



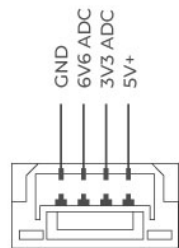
07 I2C 2



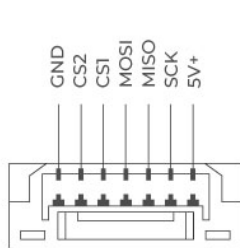
08 I2C 1



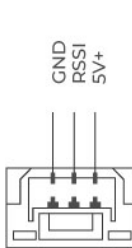
09 ADC



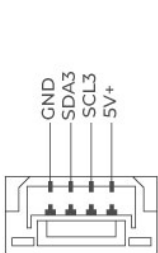
10 SPI 5



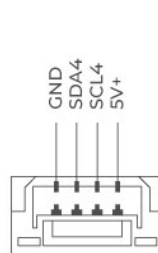
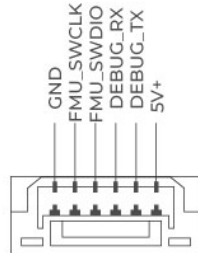
11 RSSI



12 I2C3

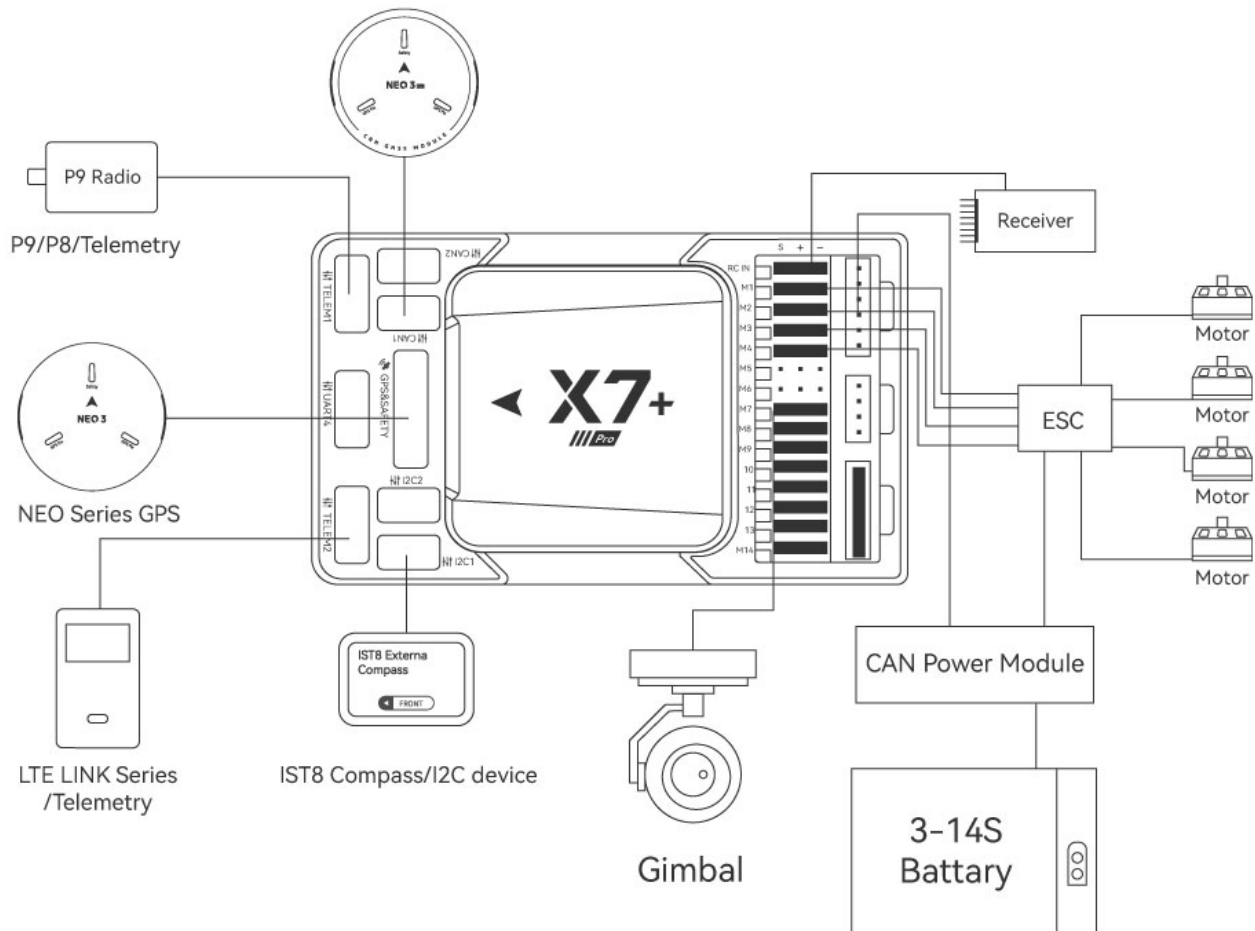


13 DEBUG&UART7 14 I2C4



## Hardware connection diagram

Take the quadcopter as an example:



## Product connection

Interface	Connected accessories
M1-M14	PWM signal output port, They can be connected to ESC and servo
RCIN	Connect PPM / DSM / SBUS remote control receiver
Power A	Connect HV_PM or other analog ammeter
Power C	Connect to CAN protocol power management module such as CAN PMU Lite or CAN PMU
GPS&SAFETY	Connect GPS and safety switch
TELEM1	Connect P9 or other data transmission

TELEM2	Connect LTE LINK series or data transmission
I2C1/2/3/4	Connect IST8310 compass or other I2C devices
CAN1/CAN2	Connect to CAN GPS or other CAN devices (such as NEO V2 PRO/NEO 3 PRO)
UART4	Digital transmission or GPS2, etc.
RSSI	Telemetry signal strength input, receiver with RSSI output

## Certification



Product has passed  
CE certification



Product has passed  
CE certification



CUAV has passed  
ISO 9001 quality management  
system certification

## More information

CUAV official website: [www.cuav.net](http://www.cuav.net)

For more usage and assembly instructions, please visit the document center: [doc.cuav.net](http://doc.cuav.net)